

Edward M Kim

770-851-4037 | edwardmkim@cmu.edu | www.linkedin.com/in/edward-m-kim/ | emk10772.wixsite.com/mysite

EDUCATION

Carnegie Mellon University

Bachelor of Science in Electrical and Computer Engineering

QPA: 3.89

Pittsburgh, PA

May 2029

EXPERIENCE

Carnegie Mellon Racing FSAE

Low Voltage Battery Management System Co-Lead

May 2026 - Present

- Designed the Battery Management System for a custom 24V battery using Altium Designer
- Added current sense, onboard undervoltage relay, and charging circuitry without increasing board footprint

Grounded Low Voltage Subteam Member

Aug 2025 - Aug 2026

- Integrated the electrical systems connecting the sensor suite and compute responsible for driverless operations
- Documented 300+ cross-car connections and created electrical harness for the 2026 car

CMU Robotics Institute Biorobotics Lab - Eigenbot Project

Feb 2026 - Present

Undergraduate Research Assistant

- Researched kinematics of modular robots using combinations of locomotive modules on the Eigenbot platform
- Debugged six legs consisting of five modules each using custom Eigenscope software and Eigenbot firmware

Georgia Tech CRAB Lab

Jun 2024 - July 2025

Internship

- Researched bipedal robot locomotion on granular slopes to increase stability in extreme environments
- Designed retractable cleats to allow shallower gaits which improved stability at slopes up to 30 degrees
- Performed data analysis with MATLAB to evaluate gait efficiency and applied results to improve foot design

FRC Robotics: Team 1683 Techno Titans

Aug 2021 - May 2025

Electrical Lead

- Managed the design of 12V electrical systems for the team robot focusing on maintenance accessibility
- 2-time event winner, 3-time World Championship qualifier, 6-time event finalist
- Won Impact, Engineering Inspiration, Excellence in Engineering, Industrial Design, and Quality Awards

ACTIVITIES

Build18 (Hackathon) (Asteria Lab's Choice Award)

Jan 2026

- Designed a cable-driven whiteboard drawing robot capable of replicating images
- Created a edge detection + pixel following algorithm along with kinematics for the cable motion

MakeMIT (Hackathon) (Best Use of Gemini API Award)

Feb 2026

- Made a vision-assisted automated sorting trash can with a visual display and tracker
- Used Gemini API to prompt sorting of items from a video stream of the trash can

Red Robot Hackathon (1st Place)

Nov 2025

- Designed a robot in 48 hours to compete in a game revealed at the start of the event
- Coded custom drive control schemes along with three distinct autonomous functions

SKILLS & INTERESTS

PCB Design & CAD: Altium, KiCAD, SolidWorks, Onshape

Programming Languages: MATLAB, Java, Python

Languages: Fluent English, Proficient Korean

Interests & Hobbies: Hiking, Archery and Shooting Sports, Visiting National & State Parks